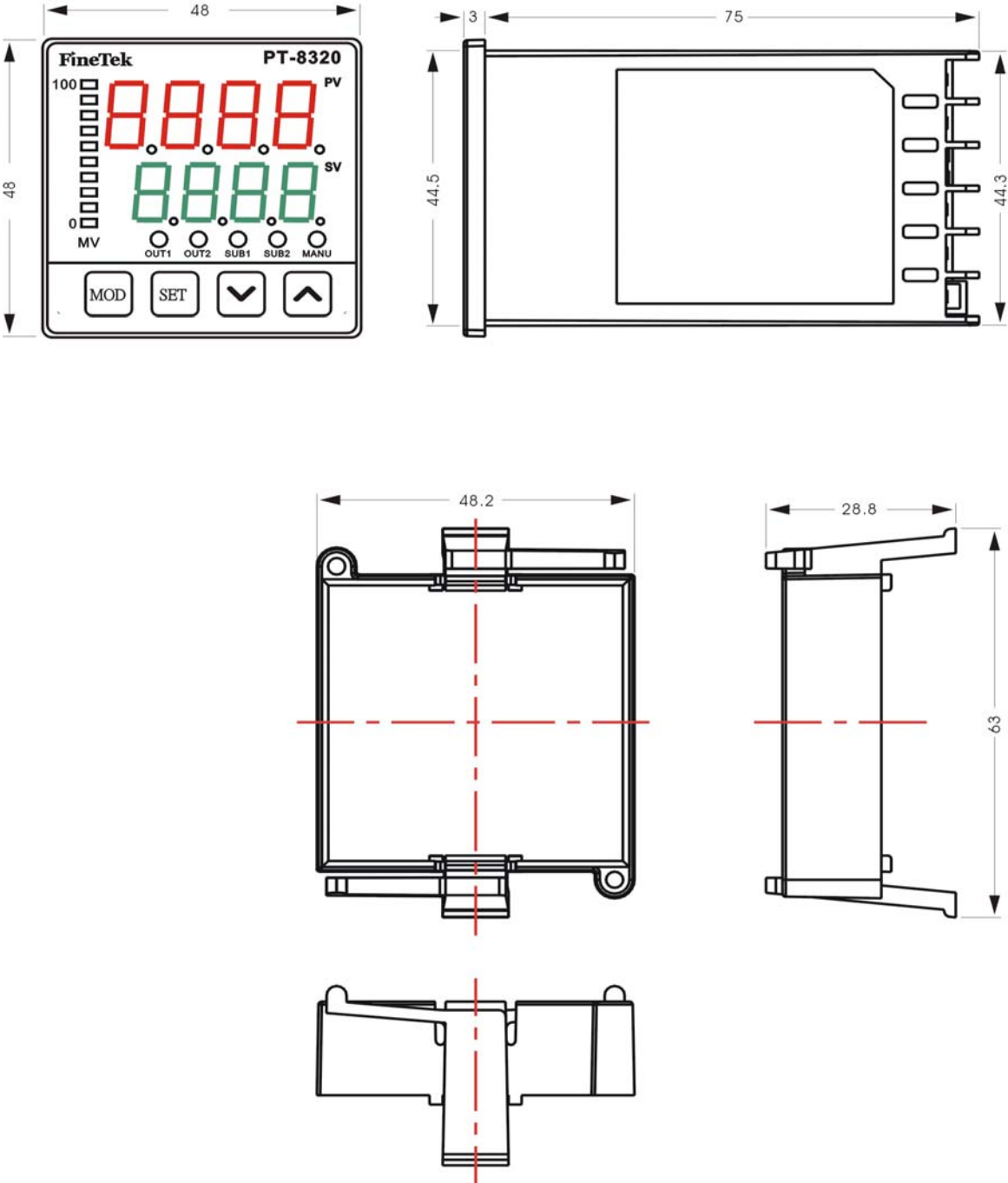


PT-8320

User Manual



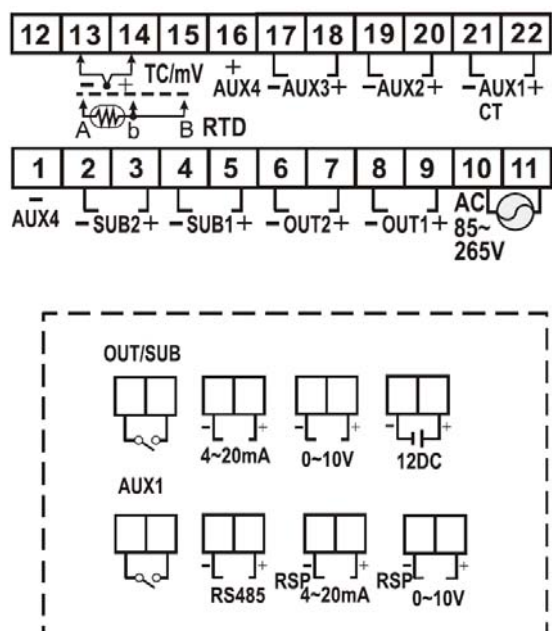
DIMENSION / PANEL CUTOUT



The diagram shows the PT-8320 digital display unit with the following components labeled:

- ①: PV (Process Variable) label
- ②: SV (Set Point) label
- ③: MANU (Manual) button
- ④: Up arrow button
- ⑤: Down arrow button
- ⑥: SET button
- ⑦: MOD button
- ⑧: MV (MilliVolts) label
- ⑨: Scale indicator (0 to 100) with a decimal point

- ### EXPLANATION FOR TERMINAL WIRING :



- 3

STANDARD SPECIFICATIONS		
Power Supply		85~265V AC 50/60 Hz
Power Consumption		7VA Maximum
Display		Upper : Red 4 digit of 7 segment display Bottom : Green 4 digit of 7 segment display 10 segment bar-graph display
Input Signal		Thermocouple : J, K, B, N, R, S, T, E RTD : PT100, JPT100 Direct Voltage : 0~230mV
Control Output	Relay	Output SPST-NO,5A/250V AC
	Pulse Output(Drive SSR)	12VDC(NPN),20mA (MAX.)
	Analog	4~20mA ,0~10V DC (MAX.600Ω)
Alarm Output		SPST-NO,5A/250V AC
Alarm Delay Time		0 ~ 99 second
Alarm Output Hysteresis Adjustment		0 ~ 9999 degree C
Communication Interface		RS485(MODBUS)
Working Temperature		0 ~ 50℃ (20~85% RH)
Cycle Time of Output Control		0 ~ 50.0 seconds
Digital		0 ~ 3 digital
Digital Filter		1 ~ 100 times
Control Method		ON/OFF or PID+Fuzzy(Auto Tuning)
Input Compensation		-1999 ~ 9999
Fraction Value		0.0 ~ 999.9
Setting Range		-1999 ~ 9999
Accuracy		0.3%FS ± 1digit
Sampling Interval		400ms
Memory Retention		EEPROM

OTHER FUNCTIONS	
Sensor Error Detection	Error code displayed on PV, with sensor error alarm output ability.
Detect the loop break and Heater Break Alarm	HBA(Heater Break Alarm), Current error of heater can be detected via CT transformer. Or using LBA(Loop Break Alarm) to detect system failure via software.
Remote Set Point (RSP)	Remote Setting Voltage 、Current signal in order to change SV value
EVENT function	Remote control for executing specific command
Re-transmission	Re-transmit the voltage 、current after the exchange of PV 、SV

A. ANUE DESCRIPTION

Main parameters selection

Main Parameters	Name of Parameter	Description of Parameter
	PV value	Present value
	SV value	Setting value
LV-0	LV-0	Status information
LV-1	LV-1	PID setting
LV-2	LV-2	Advance setting for control
Prog	Prog	Ramp & Soak setting
ALM	ALM	Alarm setting
StUP	StUP	Hardware construction setting
EXPA	EXPA	Expansion function setting
CoMM	CoMM	Communication setting
LoCK	LoCK	Lock function
SCAL	SCAL	Analog auxiliary input setting
rSP	rSP	Remote Set Point auxiliary input setting
Ct	Ct	Current transformer input setting

Under operating mode, please press MOD button in order to exchange above

Main menu selection

B. **LV-0 Parameters block description**

Parameters Display	Name of Parameters	Description of Parameters	Display Range	Default
P t n	Pattern	Display the present executing pattern	0~8	0
S t E P	Step	Display the present executing step	0~16 / S.U.	0
L i n k	Link	Display the present link setting	0~8	0
P t a g	Program	Ramp & Soak control On/Off	1 S t / 1 U n / H o l d	rSt
A d U	Advance	Skip to next step	o n / o f f	OFF
t S t b	Standby time	Display waiting time for start (minute)	0~9999	0
t E L P	Elapse time	Display schedule of executing time (minute)	0~9999	0
1 P t	Repeat time	Display style executed time	0~9999	0
E.U - H	Heater MV	Display heater output	0.0~100.0	0
E.U - C	Cooler MV	Display cooler output	0.0~100.0	0

LV-0 section shows controller status, mainly for Ramp/Soak information.

To go to LV-0, please press MOD once under SV/PV, the details are listed as below:

- **P t n** : Indication of the on-going pattern
0 : Not in the Ramp/Soak control mode, which means oPEr = onoF or Pid
- **S t E P** : Indication of the on-going step
0 : Ramp/Soak control not starts yet.
SV : Maintain the last SV (EXPA->Pend=SV) after patterns are completed.
1、3、5、7、9、11、13、15 : Ramp step
2、4、6、8、10、12、14、16 : Soak step
- **L i n k** : Next pattern ° (0: there is no next pattern)
- **P t a g** : Program control : Change is effective while LV2->oPEr not be onoF or Pid.
rSt : Reset ramp/soak status, and control/alarm output stop action.
rUn : Ramp/soak control begins or continues.
Hold : Hold ramp/soak timing
- **A d U** : Skip to next step.
Ramp=>Soak : SV becomes the setting of the next soak step.
Soak=>Ramp :
EXPA=>PVSt=PV, PV reaches soak value after ramp time from the current PV.
EXPA=>PVSt=SV, PV reaches soak value after ramp time from the current SV setting.
- **t S t b** : Remaining time before controller actuates (min).
- **t E L P** : Time performed of the on-going step (min)
- **1 P t** : Remaining repeat times.
- **E.U - H** : Percentage of manipulate value for the heater.
- **E.U - C** : Percentage of manipulate value for the cooler.

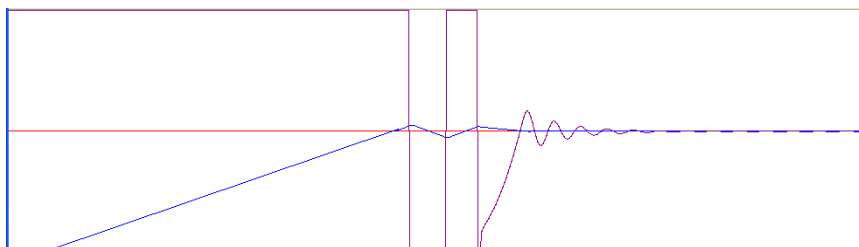
C. **LV-1 Parameters block description**

Parameters display	Name of Parameters	Description of Parameters	Display range	Default
tun	Tun	Auto Tuning	on/off	OFF
P	Proportional	Proportional parameter	0~999.9	2.0
I	Integral Time	Integral parameter (second)	0~9999	100
D	Derivative	Derivative parameter	0~9999	10
tAU	Tau	Fuzzy parameter	0.00~9.999	0.060
CoEF	Cooling Coefficient	Cooling parameter	0.0~99.99	1.00
MArE	MARE	Manual reset	0.0~100.0	0
oFS.t	Auto Tune Offset	SV Offset during Auto-tuning	-1999~9999	0
HYS	Heater Hysteresis	Control output hysteresis for heater	0~9999	0
CHYS	Cooler Hysteresis	Control output hysteresis for cooler	0~9999	0
H-Pd	Heater period	Cycle time of control heater output (second)	0.1~50.0	5.0
C-Pd	Cooler period	Cycle time of control cooler output (second)	0.1~50.0	5.0
dban	Dead band	Dead band control	on/off	OFF
db-H	Heater dead band	Dead band of heater	-1999~9999	0
db-C	Cooler dead band	Dead band of cooler	-1999~9999	0
CT	CT current monitor	Display CT		-1.
Hb	Heater burnout	Heater break setting	0~55.0	0

LV-1 section of parameters are used for basic control. **P·I·D·tAU·CoEF** parameters affect PID+Fuzzy control algorithm performance. These parameters can be auto-calculated by the auto-tune function, without the need of complex PID tuning. Fuzzy compensation control makes system response faster and more reliable.

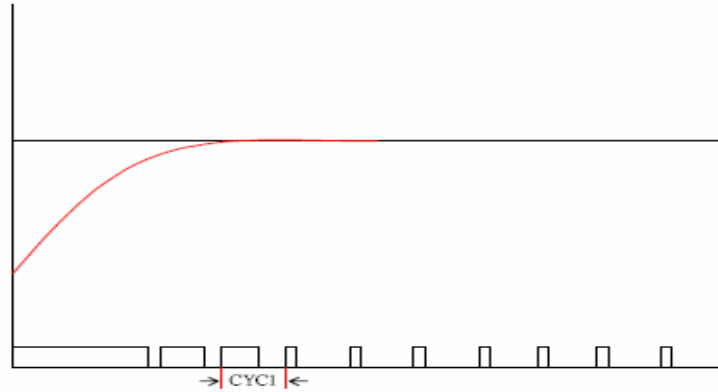
To go to LV-1, press MOD twice under SV/PV, and its sub options are listed below:

➤ **tun** : Auto tuning **tun** on : Auto tuning on **off** : Auto tuning off.



When auto tuning is on, the controller will start heating and cooling around the setting SV. After two cycles, PID parameters can be calculated. With these PID parameters, the controller can stabilize the system to a desired process value. You can also adopt the oFSt function (especially used during the auto tuning process), to prevent system over-heat during the auto tuning process.

- **P** : Proportional Gain parameter ◦ Can be calculated by auto tuning or adjusted manually. This parameter is responsible to the system deviation. When offset occurs, proportional regulator responds to reduce the offset.
- **I** : Integral parameter ◦ Can be calculated by auto tuning or adjusted manually. When steady offset exist in a consistent temperature, Integral regulator will start compensating until offset is fixed.
- **D** : Derivative parameter ◦ Can be calculated by auto tuning or adjusted manually. Derivative regulator can predict the system trend by rate of change; derivative regulator will fix the offset in advance, before offset happens.
- **τ FU** : Fuzzy factor parameter. Can be calculated by auto tuning or adjusted manually.
Fuzzy control compensates the insufficiency of PID controller and helps to reach the target based on the deviation and rate of change.
Bigger Tau, more Fuzzy compensation!
- **COEF** : Cooling coefficient. Can be calculated by auto tuning or adjusted manually.
Cooler proportional gain = P / Coef
This function is used in cooling control, to tell the performance of cooler.
- **MRST** : Manual reset.
When Integral $i=0$, and $PV > SV$, then $MV = MArE$.
- **OFST** : SV offset setting during Auto tuning
When this function is set up, auto tuning will make the system to oscillate around $SV + OFST$. For example, $SV = 200^{\circ}\text{C}$; $OFST = -10^{\circ}\text{C}$. Auto tuning will calculate as $SV + OFST = 200 + (-10) = 190^{\circ}\text{C}$, to avoid over-heating.
- **HYS** : Hysteresis for heater on/off control.
- **CHYS** : Hysteresis for cooler on/off control.
During ON/OFF control, control output should be turned off when $PV > SV$, and turned on when $PV < SV$. To avoid frequent ON and OFF control, hysteresis can be set. When HYS is set, $PV > SV + HYS$ to turn off the control output, and turned on when $PV < SV - HYS$.
- **H - Pd** : Heater control cycle time(sec)
- **C - Pd** : Cooler control cycle time(sec)
For any control output that is not in linear analog signal such as relay and 12V pulse output, signal output status will be ON/OFF only. For better PID result, Time Proportional is used. For example, period is set to be 5 seconds and PID is 30%. (ON)= 30%. $5 * 0.3 = 1.5$ sec. (OFF)= 70% $5 * 0.7 = 3.5$ sec.
Control output reacts quicker as cycle time gets shorter. When mechanical contact output is used, please consider issue of mechanical life.

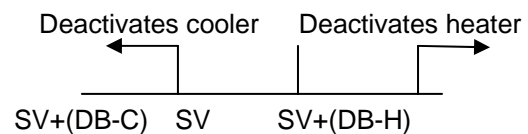
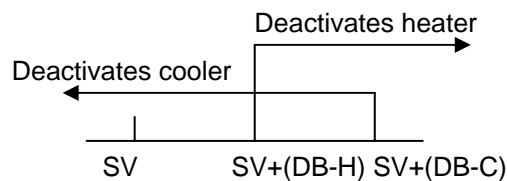


- $\text{db} \text{ on}$: Enable/disable dead band control.
- $\text{db} - \text{H}$: Dead band for heater.
- $\text{db} - \text{C}$: Dead band for cooler.

Heating and cooling range can be controlled via dead band setting
 Heater dead band control : If $PV > SV + DB-H$, heater is not active.
 Cooler dead band control : If $PV < SV + DB-C$, cooler is not active.

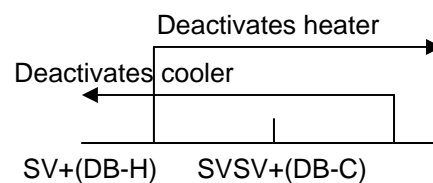
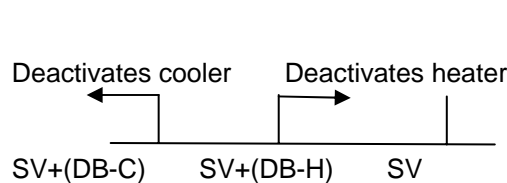
$DB-H > 0 ; DB-C > 0$
 Over $SV + DB-H$ deactivates heater
 Under $SV + DB-C$ deactivates cooler

$DB-H > 0 ; DB-C < 0$
 Over $SV + DB-H$ deactivates heater
 Under $SV + DB-C$ deactivates cooler



$DB-H < 0 ; DB-C < 0$
 Over $SV + DB-H$ deactivates heater
 Under $SV + DB-C$ deactivates cooler

$DB-H < 0 ; DB-C > 0$
 Over $SV + DB-H$ deactivates heater
 Under $SV + DB-C$ deactivates cooler



- CT : Display CT (current transformer) input current
 Install CT input expansion module, it will display relative current value
- HB : Heater break alarm setup: when CT transformer current is lower than SV during heating, it will be considered heater break. Thus, alarm will send out.

D. **LV-2 Parameters block description**

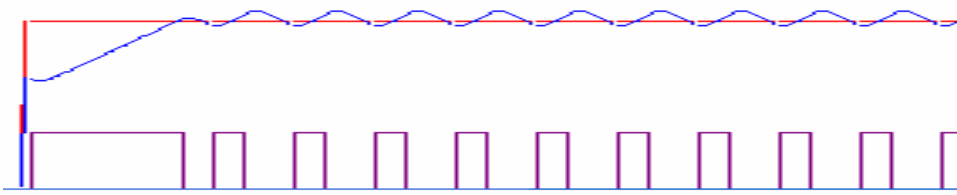
Parameter display	Name of Parameters	Description of Parameters	Display Range	Default
INP	Input	Input signal selection	K/J/E/T/S/B /N/Pt/JPt/dC	K type
OPET	Operation	Control mode selection	OnoF/P, d/Pt Pg/P-onF	OnoF
RL	Remote/Local	SV Remote/unit input	on/off	off
SV	Set Value	Temperature setting	-1999~9999	0.0
dot	Dot	Decimal point setting	dot1-dot3	dot1
Unit	Unit	Temperature unit display	°C/°F	°C
EVL	Multiplier	PV Multiplier	-1.999~9.999	1.000
bAS	Bias	PV compensation input	-1999~9999	0.0
EdE	Mode	Control mode setting	H-C/C-onL	H-C
FLt	Filter	Digital filter	1~100	5
Stb	Standby timer	Waiting time for control starting (second)	0~9999	0
LbAt	LbA detection Time	Detection time of heater break (second)	0~9999	0
LbA3	LbA detection Width	Detection of temperature differentiation of heater break	0~9999	1.0
bAt	LED Status Bar	Bar-graph display	HEAT/Cool/Prog	HEAT
TH	Transfer SV Hi	Re-transmit SV high value	-1999~9999	100.0
TL	Transfer SV Lo	Re-transmit SV low value	-1999~9999	0

LV-2 section is for advanced control parameters, ON/OFF or PID control mode can be configured to achieve the requirement.

Under SV/PV mode press 3 times of MOD button, it is for main menu of LV-2, the sub-selection as following :

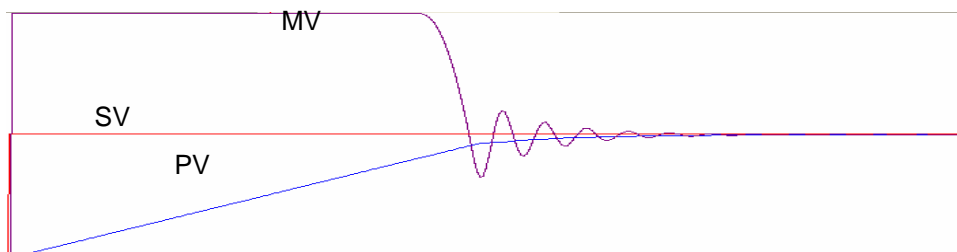
- **INP** : Input signal
 - **K** : K Type thermocouple input
Input range : -200~1370°C 0.3%±1Digit °
 - **J** : J Type thermocouple input
Input range : -210~1200°C 0.3%±1Digit °
 - **T** : T Type thermocouple input
Input range : -200~400°C ±2°C±1Digit °
 - **E** : E Type thermocouple input
Input range : -200~1000°C 0.3%±1Digit °
 - **R** : R Type thermocouple input
Input range : -50~1760°C 0.3%±1Digit °
 - **S** : S Type thermocouple input
Input range : -50~1760°C 0.3%±1Digit °
 - **B** : B Type thermocouple input
Input range : 250~1820°C ±8°C±1Digit °
 - **N** : N Type thermocouple input
Input range : -200~1300°C 0.3%±1Digit °
 - **PtPt** : PT Type thermocouple input
Input range : -200~850°C 0.3%±1Digit °
 - **JPtPt** : JPT Type thermocouple input
Input range : -200~850°C 0.3%±1Digit °
 - **dC** : DC Type voltage input
Input range : 0~230mV 0.3%±1Digit °
- **OPET** :
 - OnoF** : ON-OFF ; **P, d** : PID
 - PtPg** : Program ; **P-onF** : Program-ONOFF

On/Off mode



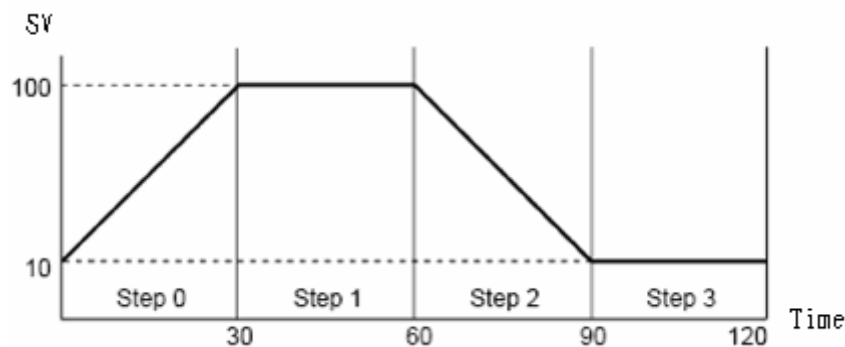
On/Off mode control is a very common and simple control mode. When the control output is programmed as the heating output and the temperature lower than setting value, control output start to activate; if the temperature is higher than setting value, control output deactivate in order to control the temperature. It also can adjust hysteresis band to reduce the overshooting on the system to achieve the best control and stability.

PID mode



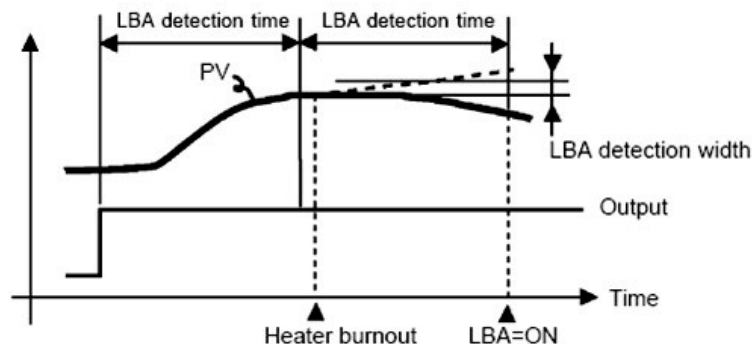
PID control is corresponding to three constants which are proportional, integral, derivative. P is to handle the immediate error, I is to learn from the past and D is to handle the future. When control output is the heating output, the PT-series will apply PID+ Fuzzy algorithm to calculate a MV value (manipulate value) to be used in determining whether the control output should be strong or weak in order to constantly calculating the deviation of stability and prediction. The built-in Fuzzy control is to enhance the system in stability for achieving the best control and efficient.

Program /Program ONOFF Mode



Program mode offers 8 patterns temperature control. Every pattern includes temperature setup, time of ramp, time of soak. Measurement unit is minute. The 8 patterns temperature control allows the system to reach the set temperature within the set time of ramp(increase/decrease), and to maintain the set temperature within the set time of soak. It can also utilize Wait Width(EXPA->WAit) to let the system stay close to the setup even if the system is unable to follow the setup perfectly. There are 8 sub-patterns for set up in one pattern. Via Link function, 64 sub-patterns temperature control can be given with ON/OFF and PID control as optional.

- **ℓ - ℓ** : Remote(RSP) or local SV
 ℓ ℓ : Remote mode (RSP) ; **ℓ ℓ ℓ** : Local mode ◦
- **ℓ.ℓ** : Temperature set value ; Set value between ◦
- **ℓ ℓ ℓ** : Decimal point set value ◦
 ℓ ℓ ℓ 0 : decimal point 0
 ℓ ℓ ℓ 1 : decimal point 1
 ℓ ℓ ℓ 2 : decimal point 2
 ℓ ℓ ℓ 3 : decimal point 3
- **ℓ ℓ ℓ** : Measurement Unit setup ◦ °C/°F
- **ℓ.ℓ ℓ** : PV magnification adjustment ◦
- **ℓ ℓ ℓ ℓ** : PV Offset input ◦ When PV's current value and expected value does not match, PV offset input function can be utilized for adjustment. $PV = PV * MUL + biAS$
- **ℓ.ℓ ℓ ℓ** : Control setup ◦
 ℓ ℓ - ℓ : for system heating and cooling ◦
 ℓ ℓ ℓ ℓ : for system cooling ◦
- **ℓ ℓ ℓ ℓ** : Digital filter ; Decrease static signal ◦ 1~100 filter time can be set ◦ Digital filter can only affect PV value time update, not speed update ◦
- **ℓ.ℓ ℓ ℓ** : Wait Width ; System can be set to control when the system can be actuated. When Wait Width is set to be 0, there will be no Wait function.
- **ℓ ℓ ℓ ℓ** : LBA heater burnout time ; Set LBA burnout cycle time(second)
 ◦ when LbAt is set to be 0 ◦ there is no LBA function ◦
- **ℓ ℓ ℓ ℓ** : LBA heater burnout temperature difference ; Set LBA burnout temperature difference. When system is being heated and temperature increase is less than the temperature difference within LBA time, controller will assume heater is broken then LBA alarm signal will be sent out.



- **ℓ ℓ ℓ** : Bargraphic Indicator
 ℓ ℓ ℓ ℓ : Heating control value ◦ one light represents 10% value.
 ℓ ℓ ℓ ℓ : Cooling control value ◦ one light represents 10% value.
 ℓ ℓ ℓ ℓ : 8 modes are active.
 First light blinks : First mode of temperature increasing/decreasing is active.
 First light on constantly : First mode of temperature holding is active.
 Second light blinks : Second mode of temperature increasing/decreasing is active.
 Second light on constantly : Second mode of temperature holding is active.
- **ℓ ℓ - ℓ** : Set to re-transfer greatest SV value ;
- **ℓ ℓ - ℓ** : Set to re-transfer smallest SV value ;
 When output is the SV re-transfer analog output, SV can be transferred into the corresponding voltage and current output.
 Example : TR-H=100.0 TR-L=0.0 Liner output 0~10VDC
 SV 0.0 ~ 100.0 corresponds to 0~10V analog output

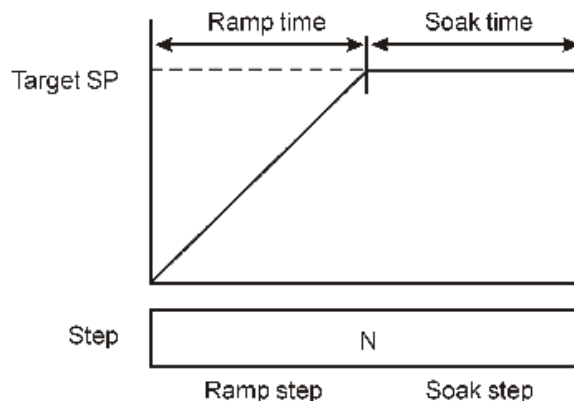
E. **P t a g** Parameter Table

Parameters display	Name of Parameters	Description of Parameters	Display range	Value
P t n	Pattern NO.	Pattern selection	1~8	1
S t E P	Number of steps	Steps needed to be performed	1~8	8
S.U 1~S.U.8	Set Value	Temperature setup	- 1999~9999	0
t t 1~t t 8	Ramp time	Time increase/decrease(min)	0~9999	0
t S. 1~t S.8	Soak time	Time of temperature holding(min)	0~9999	0
t P t	Repeat time	Repeat time	0~9999	0
L i n k	Link pattern	Link pattern	0~8	0
t S. 1 S.	Time signal step	Output signal step 1	t 1~5.8	r1
o n 1	Signal 1 ON time	Signal 1 ON time (min)	0~9999	0
o F F 1	Signal 1 OFF time	Signal 1 OFF time (min)	0~9999	0
t S. 2 S.	Time signal2 step	Output signal step 2	t 1~5.8	r1
o n 2	Signal2 ON time	Signal 2 ON time (min)	0~9999	0
o F F 2	Signal2 OFF time	Signal 2 OFF time (min)	0~9999	0

P t a g Parameter is a multi-pattern control function. Every pattern can perform 8 steps of temperature control. Via link pattern, 64 steps of temperature control can be performed.

Press MOD 4 times under SV/PV mode , sub-menu can be selected under the main menu as below:

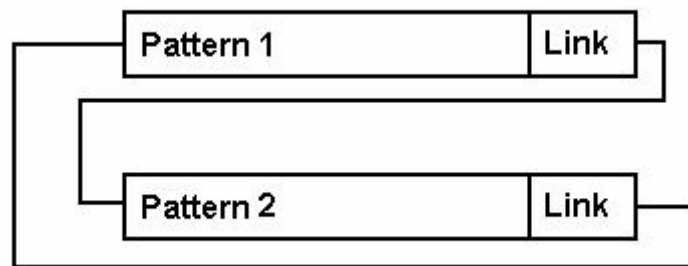
- **P t n** : 8 pattern selection : Total of 8 patterns for selection. It is also the first action pattern among the 8 patterns.
- **S t E P** : Step selection : Step 1~8. Temperature increase/decrease, temperature hold can be set in each step.
- **S.U 1~S.U.8** : Temperature setup : Set target temperature in each step.
Ex. : SV=50 PV=30 SV1=50 tr1=1 ts1=2
PV starts to increase to reach SV(increase speed is in inverse ratio to ramp time). After 1 minute, SV reaches 50 and temperature begins holding for 2 minutes.
- **t t 1~t t 8** : Time of increase/decrease(Ramp) : Set time needed(minute) in order to reach the set temperature.
- **t S. 1~t S.8** : Time of holding(Soak) : Time of hold(minute) after ramp time.



- **반복 시간** : Repeat time : Repeat time for each step
 Default setting=0 , Repeat time= 0 , Total action= 1
 Default setting=1 , Repeat time= 1 , Total action= 2, and so on.

- **링크** : Pattern Link : Pattern selection followed by completion of each pattern.

Ex. : Set Link=2 followed by Pattern 1.
 Link=1 followed by Pattern 2.



- **신호 출력 설정 / 신호 출력** : Signal output procedure : signal output setup
 r1 : Temperature increase 1
 s1 : Temperature holding 1
 r2 : Temperature increase 2
 s2 : Temperature holding 2
- **신호 대기 시간** : Signal on wait time : Signal output turns on at set wait time
- **신호 대기 시간** : Signal off wait time: Signal output turns off at set wait time.

Signal will be turned off followed by time signal 1~2. Signal will be turned on in specified step.

F. **RL E. Parameter Table**

Parameters display	Name of Parameters	Description of Parameters	Display range	Reset Value
5.0 F t	Soft Start	Alarm soft start	00/0 F F	OFF
P 0 5. 1	Position 1	Alarm position 1	- 1999~9999	0.0
H 4 5. 1	Hysteresis 1	Hysteresis 1	0000~9999	0.0
d 4 t 1	Delay Time 1	Delay time 1(sec)	0~99	0
5. t 4 1	Style 1	Style 1	5. t 4 1 ~ 5. t 4 8, 5. E t t	Sty1
P 0 5. 2	Position 2	Alarm position 2	- 1999~9999	0.0
H 4 5. 2	Hysteresis 2	Hysteresis 2(sec)	0000~9999	0.0
d 4 t 2	Delay Time 2	Delay Time 2	0~99	0
5. t 4 2	Style 2	Style 2	5. t 4 1 ~ 5. t 4 8, 5. E t t	Sty1
P 0 5. 3	Position 3	Alarm position 3	- 1999~9999	0.0
H 4 5. 3	Hysteresis 3	Hysteresis 3(sec)	0000~9999	0.0
d 4 t 3	Delay Time 3	Delay Time 3	0~99	0
5. t 4 3	Style 3	Style 3	5. t 4 1 ~ 5. t 4 8, 5. E t t	Sty1
P 0 5. 4	Position 4	Alarm position 4	- 1999~9999	0.0
H 4 5. 4	Hysteresis 4	Hysteresis 4(sec)	0000~9999	0.0
d 4 t 4	Delay Time 4	Delay Time 4	0~99	0
5. t 4 4	Style 4	Style 4	5. t 4 1 ~ 5. t 4 8, 5. E t t	Sty1

RL E. There are 4 sets of alarm parameter setting designed to fit different application condition. In addition, there is Error Alarm function(ALM->StyLE->SErr) for additional protection for your system. Press MOD 5 times under SV/PV mode to go to ALM main menu. Sub-menu:

- 5.0 F t : Alarm soft start on/off
Alarm will go off when system is within the alarm range twice.
- P 0 5. 1 : Position 1 setup.
- H 4 5. 1 : Hysteresis 1 setup.
- d 4 t 1 : Delay time 1 setup(sec).
- 5. t 4 1 : Style 1 selection(Please refer to **StyL alarm style** description).
- P 0 5. 2 : Position 2 setup.
- H 4 5. 2 : Hysteresis 2 setup.
- d 4 t 2 : Delay time 2 setup(sec).
- 5. t 4 2 : Style 2 selection(Please refer to **StyL alarm style** description).

- P 3 : Position 3 setup.
- H 3 : Hysteresis 3 setup.
- d 3 : Delay time 3 setup(sec).
- S 3 : Style 3 selection(Please refer to StyL alarm style description).
- P 4 : Position 4 setup.
- H 4 : Hysteresis 4 setup.
- d 4 : Delay time 4 setup(sec).
- S 4 : Style 4 selection(Please refer to StyL alarm style description).

6.1 5.1.1 Offset High Alarm

Alarm output on

When $PV \geq SV + POS1$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

Alarm output off

When $PV < SV + POS1 - HYS1$, alarm output stops.

Ex. :

PV= present value

SV= set value

POS1= Alarm set point

DY1= Alarm delay time

SV=60 ; POS1=10 ;

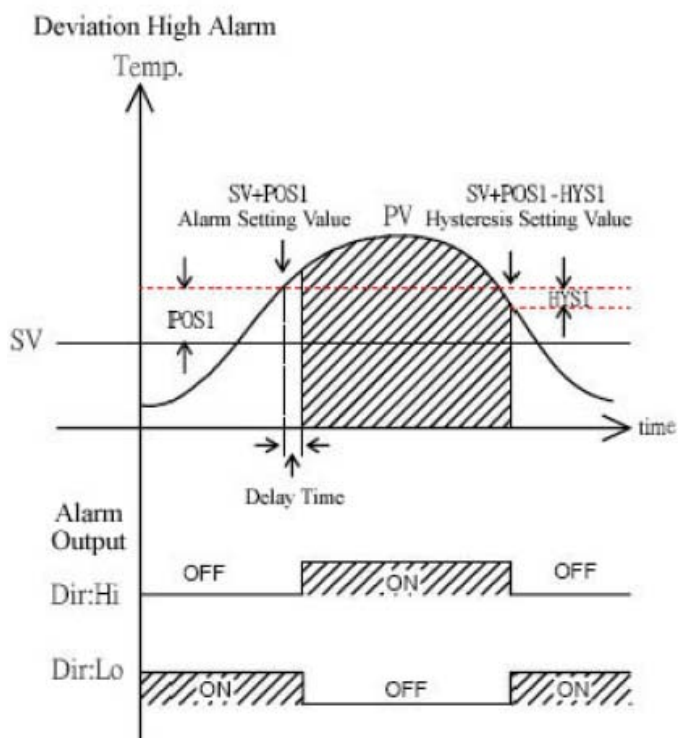
HYS1=5 ; DY1=5;

When $PV \geq 70$, DY1 starts timing.

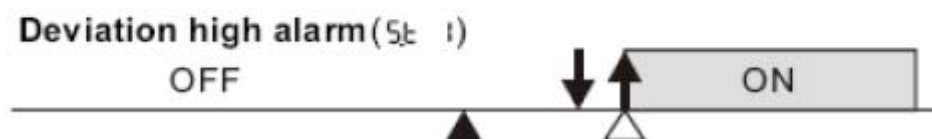
When DY1 finishes timing, alarm sends out signal output.

When $PV < 65$, alarm output stops.

5.1.1 Alarm Style



▲: SV △: Alarm Setting Value (POS.) ▼: Hysteresis Setting Value (HYS.)



6.2 5.1.2 Offset High Alarm

Alarm output on

When $PV \geq SV - POS1$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

Alarm output off

When $PV \leq SV - POS1 - HYS1$, alarm output stops.

Ex. :

PV= present value

SV= set value

POS1= Alarm set point

DY1= Alarm delay time

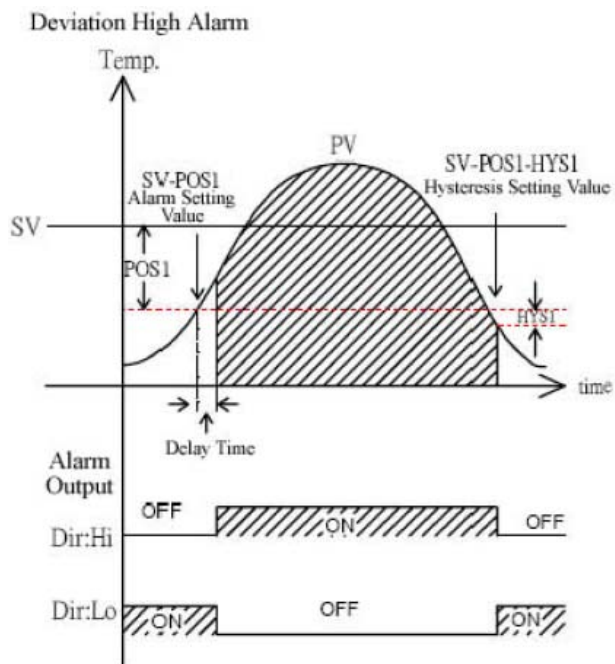
SV=60 ; POS1=10 ;

HYS1=5 ; DY1=5;

When $PV \geq 50$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

When $PV < 45$, alarm output stops.



▲: SV △: Alarm Setting Value (POS.) ▼: Hysteresis Setting Value (HYS.)



6.3 5.4.3 Offset Low Alarm

Alarm output on

When $PV \leq SV - POS1$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

Alarm output off

When $PV \geq SV - POS1 + HYS1$, alarm output stops.

Ex. :

PV= present value

SV= set value

POS1= Alarm set point

DY1= Alarm delay time

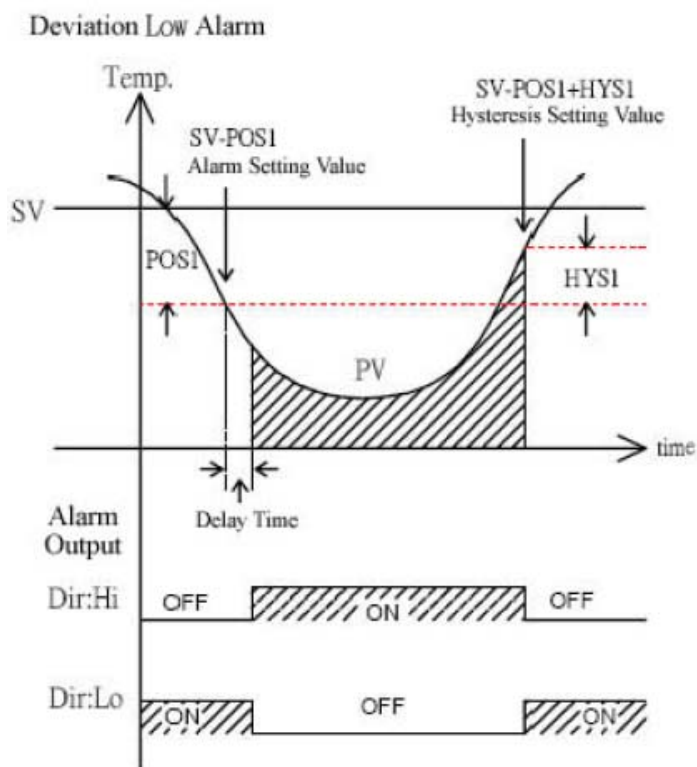
SV=60 ; POS1=10 ;

HYS1=5 ; DY1=5;

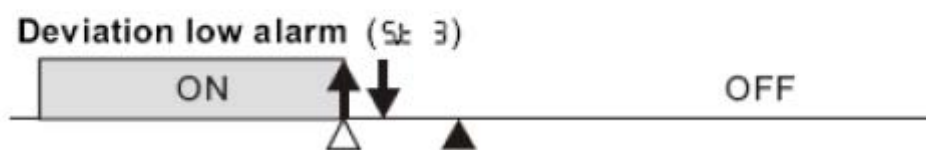
When $PV \leq 50$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

When $PV \geq 55$, alarm output stops.



▲: SV △: Alarm Setting Value (POS.) ▼: Hysteresis Setting Value (HYS.)



6.4 5.4.4 Offset Low Alarm

Alarm output on

When $PV \leq SV + POS1$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

Alarm output off

When $PV \geq SV + POS1 + HYS1$, alarm output stops.

Ex. :

PV= present value

SV= set value

POS1= Alarm set point

DY1= Alarm delay time

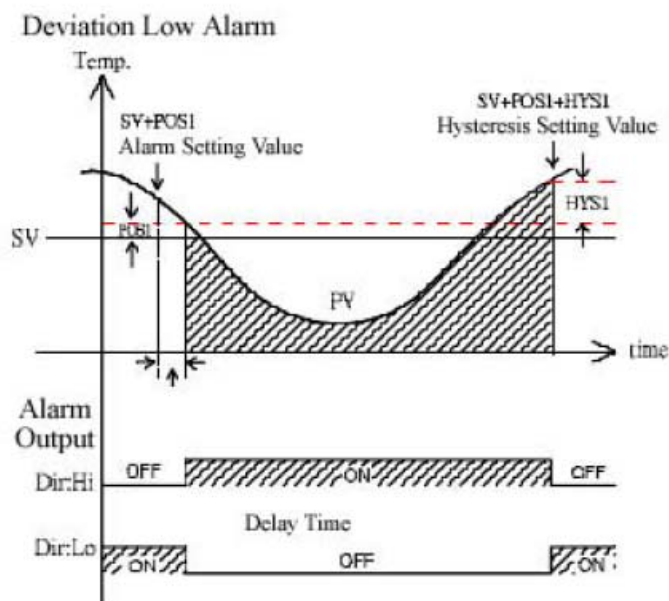
SV=60 ; POS1=10 ;

HYS1=5 ; DY1=5;

When $PV \leq 70$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

When $PV \geq 75$, alarm output stops.



▲: SV △: Alarm Setting Value (POS1) ▼: Hysteresis Setting Value (HYS1)



6.5 5.4.5 Out-Range Alarm

Alarm output on

When $PV \leq SV + POS1$ or $PV \leq SV - POS1$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

Alarm output off

When $PV \geq SV + POS1 + HYS1$ or

$PV \leq SV + POS1 - HYS1$, alarm output stops.

Ex. :

PV= present value

SV= set value

POS1= Alarm set point

DY1= Alarm delay time

SV=60 ; POS1=10 ;

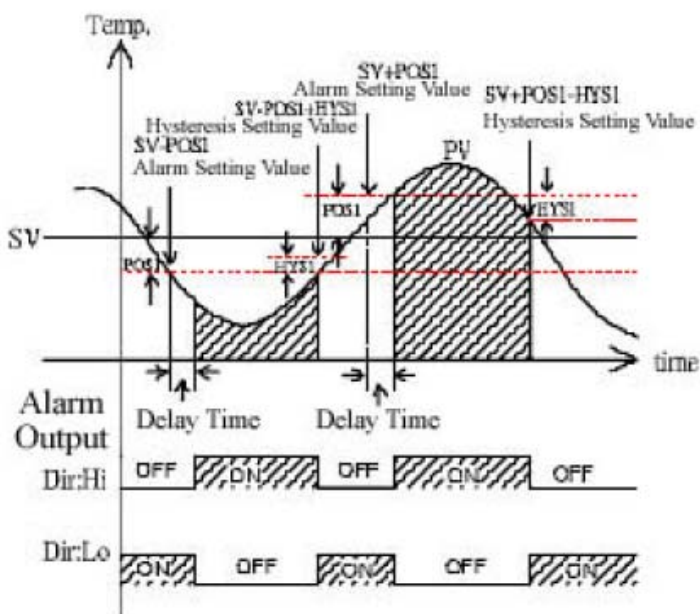
HYS1=5 ; DY1=5;

When $PV \leq 50$ or $PV \geq 70$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

When $PV \geq 55$ or $PV \leq 65$, alarm output stops.

Deviation High/Low Alarm



▲: SV △: Alarm Setting Value (POS.) ▼: Hysteresis Setting Value (HYS.)

Deviation high/low alarm (5.4.5)



6.6 5.4.5 In-Range Alarm

Alarm output on

When $PV \geq SV - POS1$ and $PV \leq SV + POS1$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

Alarm output off

When $PV \leq SV - POS1 - HYS1$ or

$PV \geq SV + POS1 + HYS1$, alarm output stops.

Ex. :

PV= present value

SV= set value

POS1= Alarm set point

DY1= Alarm delay time

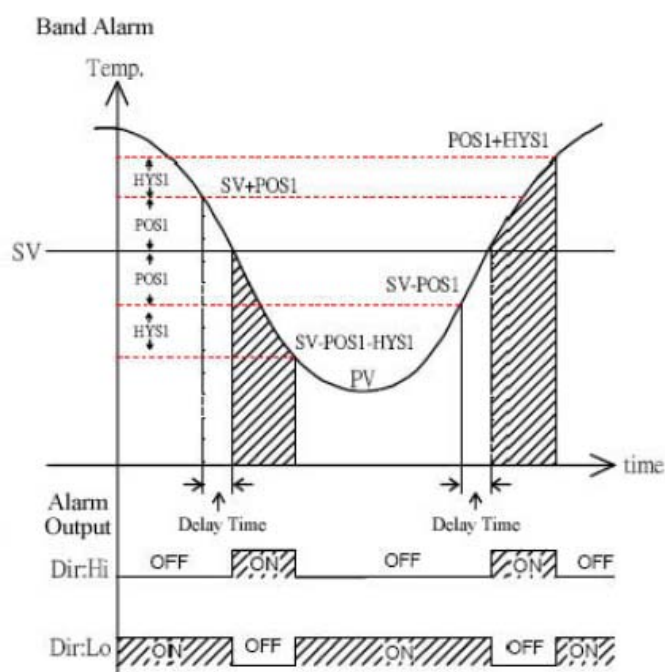
SV=60 ; POS1=10 ;

HYS1=5 ; DY1=5;

When $PV \geq 50$ and $PV \leq 70$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

When $PV \leq 45$ or $PV \geq 75$, alarm output stops.



▲: SV △: Alarm Setting Value (POS.) ↓: Hysteresis Setting Value (HYS.)



6.7 5.4.1 Absolute Value High Alarm

Alarm output on

When $PV \geq POS1$, DY1

starts timing.

When DY1 finishes timing, alarm sends out signal output.

Alarm output off

When $PV \leq POS1 - HYS1$, alarm output stops.

Ex. :

PV= present value

SV= set value

POS1= Alarm set point

DY1= Alarm delay time

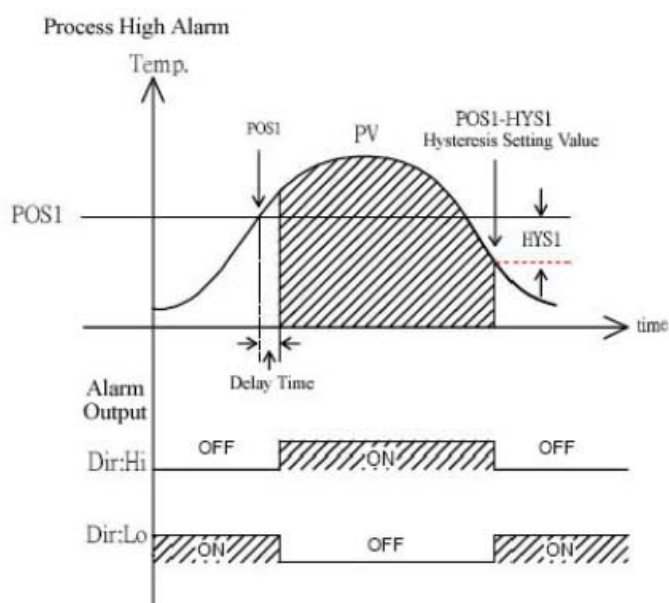
SV=10 ; POS1=60 ;

HYS1=5 ; DY1=5;

When $PV \geq 60$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

When $PV \leq 55$, alarm output stops.



▲: SV △: Alarm Setting Value (POS1) ▼: Hysteresis Setting Value (HYS1)

Process high alarm (5.4.1)



6.8 5 1 4 B Absolute Value Low Alarm

Alarm output on

When $PV \leq POS1$, DY1

starts timing.

When DY1 finishes timing, alarm sends out signal output.

Alarm output off

When $PV \geq POS1 + HYS1$, alarm output stops.

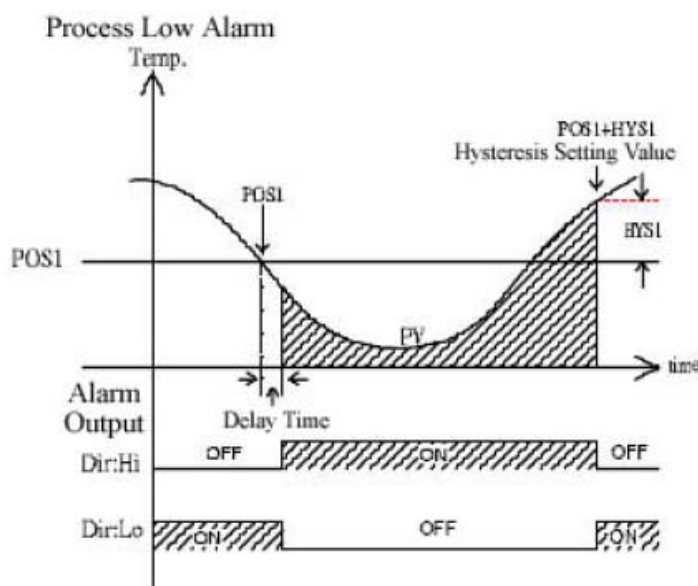
Ex. :

PV= present value

SV= set value

POS1= Alarm set point

DY1= Alarm delay time



SV=60 ; POS1=10 ;

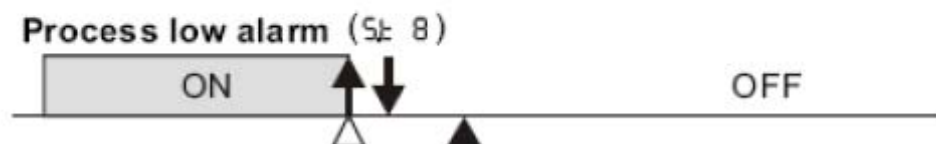
HYS1=5 ; DY1=5;

When $PV \leq 10$, DY1 starts timing.

When DY1 finishes timing, alarm sends out signal output.

When $PV \geq 15$, alarm output stops.

▲: SV △: Alarm Setting Value (POS1) ▼: (HYS1)



6.9 SErr Signal Error Alarm

Under this alarm mode, alarm will go off when PV encounters irregular condition.

When PV indicates [—] – Sensor break

[U U U U] – Exceed low limit measuring range

[o o o o] – Alarm goes off if exceeding high limit measuring range

G. **SETUP** Parameter Table

Parameters display	Name of Parameters	Description of Parameters	Display range	Reset Value
OUT 1	Out1	control/alarm/output transmission	none,HEAT,COOL,	Heat
OUT 2	Out2		AL E. 1~AL E.4,HbA,	Cool
SUB 1	Sub1		LbA,t-PUL-t-SU,	ALM1
SUB 2	Sub2		ts- 1,ts-2,PEnd,	ALM2
		SE9		
AUX 1	AUX1	AUX input	none,tSP,CE,	None
AUX 2	AUX2			
AUX 3	AUX3			
AUX 4	AUX4			
EVENT 1	Event 1	Event input	none,t-L,ERRU,	None
EVENT 2	Event 2			
EVENT 3	Event 3			
EVENT 4	Event 4			
DIR 1	Direction 1	Input direction (forward or reverse)	H, /L o	Hi
DIR 2	Direction 2			
DIR 3	Direction 3			
DIR 4	Direction 4			

SETUP Users can set parameters according to application environment and habit.

- **OUT 1** : Out 1 control/alarm/output transmission : Selectable output types
 - **OUT 2** : Out 2 control/alarm/output transmission : Selectable output types
 - **SUB 1** : Sub 1 control/alarm/output transmission : Selectable output types
 - **SUB 2** : Sub 2 control/alarm/output transmission : Selectable output types
- HEAT** : Heater control output
COOL : Cooler control output
AL E. 1~AL E.4 : Alarm output to be performed with ALM for detail setup.
HbA : Heater break alarm to be performed with CT transformer.
LbA : Loop break alarm to detect heater break by software. This function has to be performed with LV-2→LbAt and LbAW.
t - PUL : Controller has to work with analog output to transfer PV value to voltage/current value.
For module 0-10vDC 、4-20mA, please refer to SCALE.
t - SU : Controller has to work with analog output to transfer SV value to voltage/current value.
For module 0-10vDC 、4-20mA, please refer to LV-2→tr-H and tr-L.
ts- 1~ts- 2 : In specified steps, ts1~2 will send out signal after On Wait Time and ts1~2 will be turned off after Off Wait Time.

Ex.: ts1=S2 , on=2 , off=3

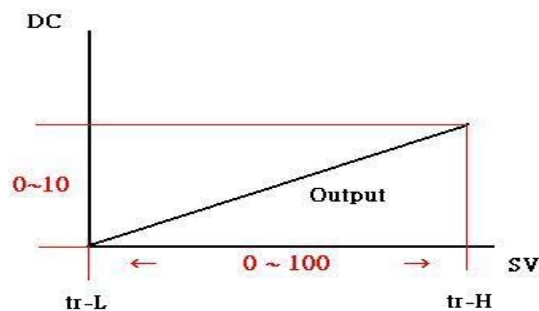
After 2 minutes in Temperature Holding Step 2, ts1 will be on. After another 1 minute, it will be off again.

After ts-1~2 goes to the next step, all signal will be off until it reaches specified steps.

PEND : When 8 steps are completed, Pend will receive a pulse signal.

Stg : When performing 8 steps, Stg will receive pulse signal when it is in ramp or soak

Ex. : To correspond SV 0.0~100.0 to 0-10VDC output, please set LV-2→tr-H = 100 ,
LV-2→tr-L = 0



➤ AUX 1 : Aux 1 input

➤ AUX 2 : Aux 2 input

➤ AUX 3 : Aux 3 input

➤ AUX 4 : Aux 4 input

Offer different signal input including remote SV value(RSP) 、remote Event, current transformer, and CT input.

↳ RSP : Remote SV value setup with 0-10V , 0-20mA module input.

Please go to rSP in main menu for detail setup.

CT : Current transformer input for current measurement with Ct module.

Please go to Ct in main menu for detail setup.

EVENT 1~EVENT 4 : Specified Event can be set with Event module.

➤ EVENT 1 : Event 1 input

➤ EVENT 2 : Event 2 input

➤ EVENT 3 : Event 3 input

➤ EVENT 4 : Event 4 input

EVENT 1~EVENT 4 : Specified Event can be set with Event module.

Under Stup→EVt1~4 in main menu , corresponding Event(Reset,Remote

-Local ,Manual, Hold, Advance) can be set ° Simply switch on to perform.

↳ - L : Switch on => LV-2->r-L=on

Switch off => LV-2->r-L=off

E. R n U : Switch on => Switch between manual and standard mode

↳ S t : Switch on => LV-0->Prog=rSt

Switch off => LV-0->Prog=rUn

H o L d : Switch on => LV-0->Prog=HoLd

Switch off=>LV-0->Prog=Retrieve Hold original setting

F L a U : Switch on => LV-0->AdV=on

➤ d , 1 : Output direction 1(Forward/reverse)

➤ d , 2 : Output direction 2(Forward/reverse)

➤ d , 3 : Output direction 3(Forward/reverse)

➤ d , 4 : Output direction 4(Forward/reverse)

Select Forward output or Reverse Output with Out1, Out2, Sub1, Sub2.

H. EHP R Parameter Table

Parameters display	Name of Parameters	Description of Parameters	Display range	Reset Value
SV - H	Set value upper limit	SV upper limit setup , SV-H>SV-L	- 9999-9999	9999
SV - L	Set value lower limit	SV lower limit setup , SV-L<SV-H	- 9999-9999	-1999
At - H	AT hysteresis	Auto Tune hysteresis	0.0~100.0	0.5
P - on	Power ON	Power on	Con/Stop/Run/E.RnU	rSt
PEnd	Pend condition	Pend condition	Stop/SV	rSt
Wait, t	Wait width	Wait width	- 9999-9999	0
PVSt	PV Start	PV/SV start	PV/SV	PV
Return	Return display	SV/PV main menu Auto return(sec)	off/10/20/30/40/50/60	0
HbL	HBA latch	HBA latch alarm	on/off	OFF
FRct	Reset default	Default vale retrieval	on/off	OFF

Users can set parameters according to application environment and habit.

- SV - H : SV value upper limit setup : To limit maximum SV value, preset value is 9999.
- SV - L : SV value lower limit setup : To limit minimum SV value, preset value is -1999.
- At - H : Auto Tune hysteresis setup : To avoid signal interruption during Auto Tune which causes faulty calculation, At-H value is preset to be 0.5. System will be heated to PV+0.5, and cooled to PV-0.5 during Auto Tune.
- P - on : Power on setup: This mode is designed for 8 patterns(Program mode). It can set Continue, Reset, Run and Manual when system is on.
 - Stop : Controller turns on. Program mode is in reset condition. Alarm will not go off.
 - E.RnU : Controller is in manual mode when it is turned on.
 - Run : Controller turns on. Program mode resets automatically.
 - Con : Restore the program status before power failure, and continue operating
(rSt、rUn、Con options are effective while LV2->oPEr=Prog or P-nF)
- PEnd : Pend status : Set controller's mode after 8 patterns finish running.
 - It can be set as Reset. Controller will return to rSt after 8 patterns complete and alarm does not go off.(LV0->Prog=rSt)
 - It can be set as SV. Controller will remain in the last SV after 8 patterns complete and continues functioning.
- Wait, t : Wait Width : When performing 8 patterns, | PV-SV | has to be smaller than Wait width in order to enter the next step and follow the setting.
Default value 0: Disable.

- **P U S E** : Ramp/Soak initial SV setting, the SV initial value of the first step or when skip into ramp step, the SV initial value accumulate from the current PV or according to the SV setting.

PV : Perform based on PV setup

SV : Perform based on SV setup

- **T E E n** : PV/SV main menu auto return : Display will automatically returned to PV/SV main menu when there is no new setup for time input. Setup range is oFF 、 10 、 20 、 30 、 40 、 50 、 60.(Default oFF Not return to PV/SV automatically , Unit : second)
- **H b L** : Alarm latch : HBA latch alarm can be set.
When latch mode is on, HBA alarm not de-energize while system outside the alarm range.
(default : OFF)
- **F R C E** : Preset default value retrieval(reset) : This mode can retrieve preset default value.

I、**【 0 E.E. List of parameters**

Parameters display	Name of Parameters	Description of Parameters	Display range	Default
, d	ID	Identification	1~255	1
b P S.	BPS.	Baud rate	Describe below	9600
5. t Y L	Style	Transmitting Style	Describe below	8n1
F o t E.	Format	Transmitting Format	Hex/Ascii	Hex
t o u t	Time Out	Setting for Time limit	100~9999	100
3. t t	Allow Write	Allow writing for parameters	o n / o f f	ON

- **, d** : Identify the address of control unit

- **b P S.** : Selection for Baud Rate communication
 - 600 : Baud rate 600
 - 1200 : Baud rate 1200
 - 2400 : Baud rate 2400
 - 4800 : Baud rate 4800
 - 9600 : Baud rate 9600
 - 19200 : Baud rate 19200
 - 38400 : Baud rate 38400

- **5. t Y L** : Selection for communication style
 - 8n1 : None parity check, Stops one bit
 - 8n2 : None parity check, Stops two bits
 - 8o1 : Odd check, Stops one bit
 - 8E1 : Even check, Stops one bit

- **F o t E.** : Selection for communication format
 - HEH. : Hex mode
 - AS.Ci : ASCII mode

- **t o u t** : Setting for time limit
- **3. t t** : Allow writing, setting the communication with parameters writing(ON/OFF)

J、**L a b E Parameters block description**

Parameter Display	Name of Parameters	Description of Parameters	Setting Range	Default
L A b E	LABEL	Lock selection	Lb00~Lb04	LB00

Through LAbe parameter setting, it is adjust the main menu selectable and good for use friendly, avoid the possibility mistake in setting function.

	LB00	LB01	LB02	LB03	LB04
PV/SV	●	●	●	●	●
LV-0	●	●		●	
LV-1	●	●	●		
LV-2	●	●	●		
Prog	●	●		●	
ALM	●	●	●		
StUP	●				
EXPA	●				
CoMM	●				
LoCK	●	●	●	●	●
SCAL	●				
rSP	●				
Ct	●				
CALI	●				
MANU	●	●	●	●	●

CALI : Calibration selection

MANU : Manual selection

K. SCL Parameter Table

Parameter Display	Name of Parameters	Description of Parameters	Setting Range	Pre-set value
SCH	Scale Hi	Greatest PV value	- 1999~9999	100.0
SCL	Scale Lo	Lowest PV value	- 1999~9999	0.0
SEnS	Sensor input voltage	Sensor AD voltage		
SCH ,	Sensor Hi	Greatest voltage input	- 1.999~9.999	0.25
SCL ,	Sensor Lo	Lowest voltage input	- 1.999~9.999	0.1
SEEn	Scale Enable	Scale enable switch	OFF / ON	OFF

➤ SCH : Greatest PV value : Set PV value in Span voltage.

➤ SCL : Lowest PV value : Set PV value in Zero voltage.

PV can be re-transmitted for t-PV(Transfer PV).

➤ SEnS : Sensor AD voltage : Set SCHi、SCLi.

➤ SCH , : Greatest voltage input : Set greatest measuring voltage in Sensor input.

➤ SCL , : Lowest voltage input : Set lowest measuring voltage in Sensor input.

➤ SEEn : Input switch : ON/OFF voltage input in PV display

Ex. 1 : PV value 0.0~ 100.0 corresponds to 0~10V DC output in SUB2 terminal

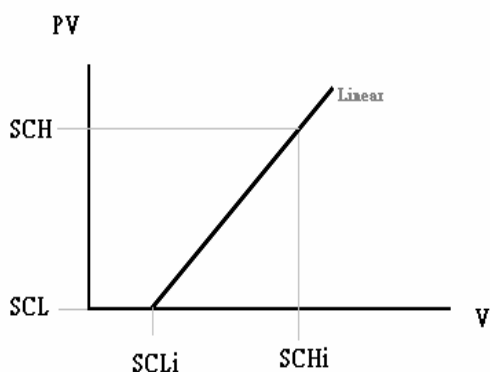
Steps :

- 1、StUP→SUB2 = t-PV in main menu
- 2、SCAL→SCH = 100.0 in main menu
- 3、SCAL→SCL = 0.0 in main menu
- 4、Complete setup

Ex. 2 : 0-10mV value corresponds to PV 0.0~200.0 in Sensor output

Steps :

- 1、Connect 0-10mV DC to PT8 in Sensor output terminal.
- 2、SCAL→SCH = 200.0
- 3、SCAL→SCL = 0.0
- 4、Input 0V to observe SCAL→SEnS and input value into SCAL→SCLi
- 5、Input 10mV to observe SCAL→SEnS and input value into SCAL→SCHi
- 6、SCAL→SCEN = ON
- 7、Back to main menu
Input 0mV, PV = 0.0?
Input 10mV, PV = 200.0?
- 8、Complete setup



L. **5.P Parameter Table**

Parameter Display	Name of Parameters	Description of Parameters	Setting Range	Pre-set value
5.C.H	Scale Hi	Greatest SV Value(RSP)	- 1999-9999	10.0
5.C.L	Scale Lo	Lowest SV Value(RSP)	- 1999-9999	0.0
R.d	AD Voltage	AD Voltage		
5.C.H,	Input Hi	Set Span Voltage	- 1.999-9.999	2.264
5.C.L,	input Lo	Set Zero Voltage	- 1.999-9.999	0.072

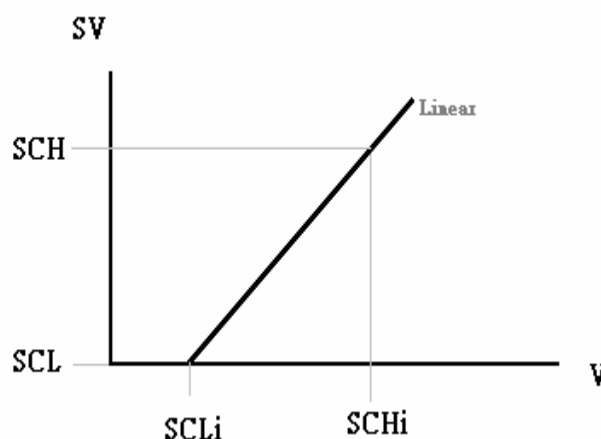
Note : LV-2 → r-L has to be turned on in order to perform each mode.

- 5.C.L : Greatest SV Value : Set greatest SV value in Span voltage.
- SCL : Lowest SV Value : Set lowest SV value in Zero voltage.
- R.d : Sensor AD Voltage : To calibrate zero, span voltage
- 5.C.H, : Set Span Voltage : Set greatest voltage output for AD.
- 5.C.L, : Set Zero Voltage : Set lowest voltage value for AD.






Ex. : Set input of 0~10vdc in AUX1
SV value: 0.0~100.0

Steps :






- 1、Connect 0-10VDC output to PT8(AUX1)(RSP 0-10Vdc)
- 2、Select rSP under StUP→AUX1 in main menu.
- 3、Select rSP→SCH = 100.0 in main menu
- 4、Select rSP→SCL = 0.0 in main menu
- 5、Input 0V to observe rSP→AD.Input value into rSP→SCLi
- 6、Input 10v to observe rSP→AD. Input value into rSP→SCHi
- 7、Select LV-2→r-L = ON in main menu
- 8、Back to PV/SV main menu
Input 0v, SV = 0.0
Input 10v,SV = 100.0
- 9、Complete setup



M. Parameter Table

Display	Name	Description	Range	Preset Value
	Scale Hi	Scale Hi(CT current)	- 1999 -9999	35.0
	Scale Lo	Scale Lo(CT current)	- 1999 -9999	0.0
	AD Voltage	AD Voltage Indication		
	Input Hi	Set Span voltage	- 1.999-9.999	2.5
	input Lo	Set Zero voltage	- 1.999-9.999	0.1

Note : Tolerance of greatest CT current input is 30mA

-  : Scale Hi : Set greatest CT value in Span voltage
-  : Scale Lo : Set lowest CT value in Zero voltage
-  : Sensor AD Voltage : To calibrate zero, span voltage
-  : Set Span voltage : °
-  : Set Zero voltage : °

Ex. : When hardware detects heater breakage, CT input utilizes AUX1 and SUB1 to send alarm signal.

Steps : (Please refer to CT input module in the right)

- 1、Connect CT transformer to PT8(AUX1) °
- 2、Select Ct under StUP→AUX1 in main menu.
- 3、Select HbA under StUP→SUB1 in main menu.
- 4、Observe AD voltage exceeds 0.100v when heater is on under Ct→AD in main menu. If AD voltage exceeds 0.100v, it means transformer is connected correctly.
- 5、Observe Ct value(HNC) when heater is off and (HNO) when heater is on under LV-1→Ct in main menu.
- 6、Input proper set value (HNC < Hb < HNO) under LV-1→Hb in main menu. Normal setup is 70% of HNO.
- 7、Complete setup.

Ex. : Calibrate CT transformer :

Transformer input is 5A ; Ratio is 1000:1

- 1、Main menu Ct→SCH = 5.0
- 2、Main menu Ct→SCL = 0.0
- 3、Input 0A to observe Ct→AD display , input value into SCLi
- 4、Input 5A to observe AD , input value into SCHi
- 5、Complete setup.

N、CAL, Parameter Table

Display	Name	Description	Range	Preset Value
R, C	Analog input calibrate	Sensor input calibration		
RoC 1	Analog output1 calibrate	Analog output1 calibration		
RoC 2	Analog output2 calibrate	Analog output2 calibration		
RoC 3	Analog output3 calibrate	Analog output3 calibration		
RoC 4	Analog output4 calibrate	Analog output4 calibration		
FUZY	Fuzzy Switch	FuzzySwitch	on/off	ON
, nF a	TEMP121 information	Temperature Information		

CAL, Calibration mode can be performed based on each input/output.

To go to Cali main menu, please press **MOD** and hold for 5 seconds under SV/PV mode.

To go back to SV/PV mode, please press and hold **MOD** for 5 seconds under Fine-Tek mode.

➤ **R, C** : Sensor Input Calibration : After calibration, voltage and resistance can be measured accurately.

Sub-menu :

1、PAS : Input correct password to enter.(password : 12)

2、0mV : Calibrate 0mv input.

3、50mV : Calibrate 50mV input.

4、r100 : Calibrate 100Ω input.

5、r300 : Calibrate 300Ω input.

6、AdjT : Temperature compensation calibration.

$PV = PV + AdjT$

(Please see Example 1 for detail)

➤ **RoC 1~RoC 4** : Analog Output Calibration : Calibration will be performed based on each analog output to get accurate Span & Zero voltage

Sub-menu :

1.AdjF : Calibrate Span voltage output(0~10v), current(4~20mA)

2.Adj0 : Calibrate Zero voltage input(0~10v), current(4~20mA)

(Please see Example 2 for detail)

➤ **FUZY** : Fuzzy Switch : Whether Fuzzy is to be activated when setting up PID.(Preset Value : ON)

















➤ **, nF a** : IC Temperature Indication : To indicate temperature information.

IC temperature for thermocouple input.

$PV = TC \text{ temperature difference} + \text{internal IC temperature}$









Example 1 : Calibrate Sensor input

Setup :

- 10 、 Connect calibrator with sensor input
- 11 、 Press and hold  for 5 seconds to enter Cali mode
- 12 、 Select AiC
- 13 、 Press  under Aic→PAS = 12
- 14 、 Set calibrator output= 0mV
- 15 、 Press  to enter Aic→0mv to edit.
Press  until value is stable, then press  to confirm.
- 16 、 Set calibrator output= 50mV
- 17 、 Press  to enter Aic→50mv to edit. Press  until value is stable, then press  to confirm.
- 18 、 Set calibrator output= 100Ω
- 19 、 Press  to enter Aic→r100 to edit.
Press  until value is stable, then press  to confirm.
Note : (Please follow RTD wiring steps when calibrating)
- 20 、 Set calibrator= 300Ω
- 21 、 Press  to enter Aic→r300 to edit.
Press  until value is stable, then press  to confirm.
Note : (Please follow RTD wiring steps when calibrating)
- 22 、 Press  to enter Aic→r300 to edit.
Press  to enter Aic→Adjt to edit error of room temperature and present temperature IC.
Note : (Please refer present temperature IC in inFo→tEMP)
- 23 、 Setup complete.

Example 2 : Calibrate OUT1 analog output 0~10v DC

Setup :

- 1 、 Connect calibrator with analog output
- 2 、 Press and hold  for 5 seconds to enter Cali mode
- 3 、 Select AoC1
- 4 、 Press  to enter AoC1→AdjF to edit. Observe calibrator voltage value, then press  、  to get 10.00v.
- 5 、 Press  to enter AoC1→Adj0 to edit. Observe calibrator voltage value, then press  、  to get 0.00v.
Press  to confirm.
- 6 、 Setup complete.

O、E.R.n.U Parameters block description

Parameter	Name of Parameters	Description of Parameters	Setting Range	Default
E.R.n.U	Manual operation	Display PV value	- 1999.9999	
HEAT	Heater MV	Control heater output manipulate value	0.0 ~ 100.0	0
COOL	Cooler MV	Control cooler output manipulate value	0.0 ~ 100.0	0

- E.R.n.U : Display PV value
- HEAT : Control heater output manipulate value
- COOL : Control cooler output manipulate value